

Correction Model Midterm Exam LA2, March 1, 2021<sup>1.</sup>

1.  $A = QR$  with  $Q$  orthonormal columns,  $R$  square upper triangular and positive diagonal elements.

a)  $A^T A = (QR)^T QR = R^T Q^T Q R = R^T R$   
Obviously  $R$  is nonsingular,  $R^T$  nonsingular,  
so also  $R^T R$  nonsingular and

$$(A^T A)^{-1} = (R^T R)^{-1} = R^{-1} (R^T)^{-1} \\ = R^{-1} (R^{-1})^T$$

b)  $A = \begin{pmatrix} 1 & 1 \\ -1 & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix}$

Note that  $A$  has linearly independent columns, call them  $a_1, a_2$ . I apply GS to get an orthonormal basis of  $\text{span}(a_1, a_2)$ .

Define  $q_1 := \frac{1}{\|a_1\|} \cdot a_1$ . Then

$$q_1 = \frac{1}{\sqrt{2}} a_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \\ 0 \\ 0 \end{pmatrix}. \text{ Note: } a_1 = \sqrt{2} q_1$$

Project  $a_2$  onto  $\text{span}(q_1)$  to get

$$p_1 = \langle a_2, q_1 \rangle \cdot q_1 = (a_2^T q_1) \cdot q_1 \\ = (1 \ 0 \ 1 \ 0) \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \\ 0 \\ 0 \end{pmatrix} \cdot \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \\ 0 \\ 0 \end{pmatrix}$$

$$= \frac{1}{2} \begin{pmatrix} 1 \\ -1 \\ 0 \\ 0 \end{pmatrix}$$

Compute  $q_2 := \frac{a_2 - p_1}{\|a_2 - p_1\|}$

$$a_2 - p_1 = \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix} - \frac{1}{2} \begin{pmatrix} 1 \\ -1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} \frac{1}{2} \\ \frac{1}{2} \\ 1 \\ 0 \end{pmatrix}$$

$$\|a_2 - p_1\| = \sqrt{\frac{1}{4} + \frac{1}{4} + 1} = \sqrt{\frac{3}{2}}$$

$$\text{So } q_2 = \sqrt{\frac{2}{3}} \begin{pmatrix} \frac{1}{2} \\ \frac{1}{2} \\ 1 \\ 0 \end{pmatrix}$$

Note that  $a_2 - p_1 = \sqrt{\frac{3}{2}} q_2$  so

$$\begin{aligned} a_2 &= p_1 + \sqrt{\frac{3}{2}} q_2 \\ &= \frac{1}{\sqrt{2}} q_1 + \frac{\sqrt{3}}{\sqrt{2}} q_2 \end{aligned}$$

This yields  $(a_1 \ a_2) = (q_1 \ q_2) \begin{pmatrix} \sqrt{2} & \frac{1}{\sqrt{2}} \\ 0 & \sqrt{\frac{3}{2}} \end{pmatrix}$ ,

so:

$$\begin{pmatrix} 1 & 1 \\ -1 & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 1/\sqrt{2} & 1/\sqrt{6} \\ -1/\sqrt{2} & 1/\sqrt{6} \\ 0 & \sqrt{2/3} \\ 0 & 0 \end{pmatrix} \begin{pmatrix} \sqrt{2} & \frac{1}{\sqrt{2}} \\ 0 & \sqrt{\frac{3}{2}} \end{pmatrix}$$

$Q$   $R$

$$c) A \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

The least squares solution to this equation is the unique solution of  $A^T A \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = A^T \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$

$$\Leftrightarrow R^T Q^T Q R \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = R^T Q^T \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\Leftrightarrow R \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = Q^T \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{aligned} \text{Now, } Q^T \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} &= \begin{pmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} & 0 & 0 \\ \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{6}} & \sqrt{\frac{2}{3}} & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} \\ &= \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{6}} \end{pmatrix} \end{aligned}$$

$$R \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{6}} \end{pmatrix} \Leftrightarrow$$

$$\begin{pmatrix} \sqrt{2} & \frac{1}{\sqrt{2}} \\ 0 & \sqrt{\frac{3}{2}} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{6}} \end{pmatrix}$$

$$x_2 = \sqrt{\frac{2}{3}} \cdot \sqrt{\frac{1}{6}} = \sqrt{\frac{2}{18}} = \frac{\sqrt{2}}{\sqrt{2}\sqrt{9}} = \frac{1}{3}$$

4.

$$\sqrt{2} x_1 + \frac{1}{\sqrt{2}} \frac{1}{3} = \frac{1}{\sqrt{2}}$$

$$\sqrt{2} x_1 = \frac{1}{\sqrt{2}} \left(1 - \frac{1}{3}\right) = \frac{2}{3\sqrt{2}}$$

$$x_1 = \frac{1}{\sqrt{2}} \frac{2}{3\sqrt{2}} = \frac{1}{3}$$

Other method: least squares solution is the unique solution of  $A^T A x = A^T b$

$$A^T A = \begin{pmatrix} 1 & -1 & 0 & 0 \\ 1 & 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ -1 & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix}$$

$$(A^T A)^{-1} = \frac{1}{3} \begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix}$$

$$A^T b = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \Rightarrow x = (A^T A)^{-1} A^T b$$

$$= \frac{1}{3} \begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$= \frac{1}{3} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} \frac{1}{3} \\ \frac{1}{3} \end{pmatrix}$$

Same of course.

2. a) We should check the three axioms for inner product:

5.

$$(i) \langle f, f \rangle \geq 0 \quad \forall f$$

$$\text{Yes: } \langle f, f \rangle = \int_0^1 f(x)^2 dx + 2f(0)^2 + f(1)^2 \geq 0$$

$$\langle f, f \rangle = 0 \Rightarrow \int_0^1 f(x)^2 dx = 0 \Leftrightarrow f(x) = 0$$

Conversely,  $f = 0 \Rightarrow \langle f, f \rangle = 0$  as well.  $\forall x \in [0, 1]$

(ii)  $\langle f, g \rangle = \langle g, f \rangle$  is obvious.

$$(iii) \langle \alpha f + \beta g, h \rangle =$$

$$\begin{aligned} & \int_0^1 (\alpha f + \beta g)(x) h(x) dx + 2(\alpha f + \beta g)(0) h(0) \\ & \quad + (\alpha f + \beta g)(1) h(1) \\ & = \alpha \left( \int_0^1 f(x) h(x) dx + 2f(0)h(0) + f(1)h(1) \right) \\ & \quad + \beta \left( \int_0^1 g(x) h(x) dx + 2g(0)h(0) + g(1)h(1) \right) \end{aligned}$$

$$= \alpha \langle f, h \rangle + \beta \langle g, h \rangle$$

$$b) \|f\|^2 = \int_0^1 1 \cdot 1 dx + 2 \cdot 1 \cdot 1 + 1 \cdot 1 = 1 + 2 + 1 = 4$$

$$\Rightarrow \|f\| = 2$$

$$\|g\|^2 = \int_0^1 x^2 dx + 1 \cdot 1 = \left[ \frac{1}{3} x^3 \right]_0^1 + 1 = \frac{4}{3}$$

$$\|g\| = \frac{2}{\sqrt{3}}$$

$$c.) \cos \Theta = \frac{\langle f, g \rangle}{\|f\| \|g\|}$$

$$\langle f, g \rangle = \int_0^1 x \, dx + 1 \cdot 1 = \left[ \frac{1}{2} x^2 \right]_0^1 + 1 = \frac{3}{2}$$

$$\Rightarrow \cos \Theta = \frac{1}{2 \cdot \frac{2}{\sqrt{3}}} \cdot \frac{3}{2} = \frac{3\sqrt{3}}{8}$$

d)  $S = \text{span}(1, x)$ . We make an orthonormal basis  $\{u_1(x), u_2(x)\}$  using Gram-Schmidt.

$$u_1(x) := \frac{1}{\|1\|} \cdot 1 = \frac{1}{2}$$

Let  $p_1(x)$  be the projection of  $x$  onto  $\text{span}\left(\frac{1}{2}\right)$

$$\begin{aligned} p_1(x) &= \langle x, \frac{1}{2} \rangle \cdot \frac{1}{2} \\ &= \int_0^1 \frac{1}{2} x \, dx + 1 \cdot \frac{1}{2} = \left[ \frac{1}{4} x^2 \right]_0^1 + \frac{1}{2} \\ &= \frac{3}{4} \end{aligned}$$

$$\text{Define then } u_2(x) = \frac{x - \frac{3}{4}}{\|x - \frac{3}{4}\|}$$

$$\begin{aligned} \|x - \frac{3}{4}\|^2 &= \int_0^1 \left(x - \frac{3}{4}\right)^2 \, dx + 2 \cdot \left(-\frac{3}{4}\right)^2 + \left(\frac{1}{4}\right)^2 \\ &= \left[ \frac{1}{3} \left(x - \frac{3}{4}\right)^3 \right]_0^1 + 2 \cdot \frac{9}{16} + \frac{1}{16} \end{aligned}$$

7.

$$\begin{aligned} &= \frac{1}{3} \left(\frac{1}{4}\right)^3 - \frac{1}{3} \left(-\frac{3}{4}\right)^3 + \frac{18}{16} + \frac{1}{16} \\ &= \frac{1}{3} \frac{1}{64} + \frac{1}{3} \frac{27}{64} + \frac{72}{64} + \frac{4}{64} \\ &= \frac{1}{3} \frac{1}{64} + \frac{9}{64} + \frac{72}{64} + \frac{4}{64} \\ &= \frac{1}{64} \left(85 + \frac{1}{3}\right) = \frac{1}{64} \frac{256}{3} = \frac{4}{3} \end{aligned}$$

$$\Rightarrow \left\|x - \frac{3}{4}\right\| = \frac{2}{\sqrt{3}}$$

$$U_2(x) = \frac{1}{2} \sqrt{3} \left(x - \frac{3}{4}\right)$$

7.

$$3) \quad A = \begin{pmatrix} 2 & 1 & 0 \\ -1 & 1 & 1 \\ 1 & 0 & 0 \end{pmatrix}$$

$$a) \quad \det(A - sI) = \det \begin{pmatrix} 2-s & 1 & 0 \\ -1 & 1-s & 1 \\ 1 & 0 & -s \end{pmatrix}$$

$$= (2-s)(1-s)(-s) + (-s) + 1$$

$$= -s^3 + 3s^2 - 3s + 1$$

$$b) \quad -s^3 + 3s^2 - 3s + 1 = (1-s)^3$$

Hence there is one eigenvalue:  $\lambda = 1$ .

$$c) \quad \text{Solve } \begin{pmatrix} 2 & 1 & 0 \\ -1 & 1 & 1 \\ 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = 1 \cdot \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

$$2x + y = x \quad \Rightarrow \quad x = -y$$

$$-x + y + z = y$$

$$x = z$$

So: any eigenvector is of the form

$$\lambda \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} \quad \lambda \neq 0.$$

d) Not diagonalisable because  $A$  does NOT have 3 linearly independent eigenvectors.



4.  $A$  is unitary, i.e.  $AA^\dagger = A^\dagger A = I$ .

a) Let  $\lambda$  be an eigenvalue and  $Ax = \lambda x$ ,  $x \neq 0$ .

$$\text{Then } (Ax)^\dagger Ax = x^\dagger A^\dagger Ax = \|x\|^2.$$

$$\text{Also } (Ax)^\dagger Ax = (\lambda x)^\dagger \lambda x = |\lambda|^2 \|x\|^2.$$

$$\text{Hence } |\lambda|^2 = 1 \text{ so } |\lambda| = 1.$$

b) Assume  $|\lambda| = 1$ . Then  $\lambda \neq 0$ . Also  $|\lambda|^2 = 1$   
so  $\bar{\lambda}\lambda = 1$ . This yields  $\bar{\lambda} = \frac{1}{\lambda}$

c) Let  $\lambda_1 \neq \lambda_2$  eigenvalues and  $x_1, x_2$  corresponding eigenvectors. Need to show  $x_1^\dagger x_2 = 0$ .

$$\text{Note that } Ax_1 = \lambda_1 x_1 \text{ and } Ax_2 = \lambda_2 x_2.$$

$$\text{Thus } (Ax_1)^\dagger Ax_2 = x_1^\dagger A^\dagger Ax_2 = x_1^\dagger x_2.$$

$$\begin{aligned} \text{Also } (Ax_1)^\dagger Ax_2 &= (\lambda_1 x_1)^\dagger \lambda_2 x_2 \\ &= \bar{\lambda}_1 \lambda_2 x_1^\dagger x_2 = \frac{\lambda_2}{\lambda_1} x_1^\dagger x_2. \end{aligned}$$

$$\text{Hence } x_1^\dagger x_2 = \frac{\lambda_2}{\lambda_1} x_1^\dagger x_2. \text{ Since } \frac{\lambda_2}{\lambda_1} \neq 1$$

$$\text{we must have } x_1^\dagger x_2 = 0$$

d) Yes:  $A^\dagger A = AA^\dagger$  so  $A$  is normal,  
so unitarily diagonalisable.